Bachelor Project 2012

Analysis of the Euclidean Feature Transform algorithm

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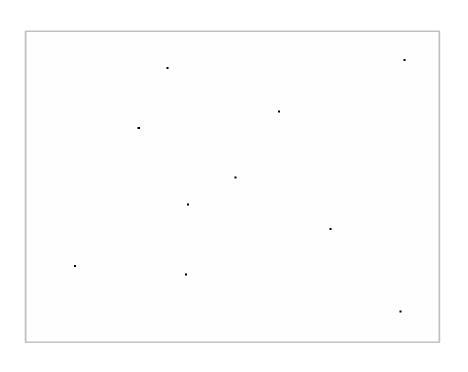
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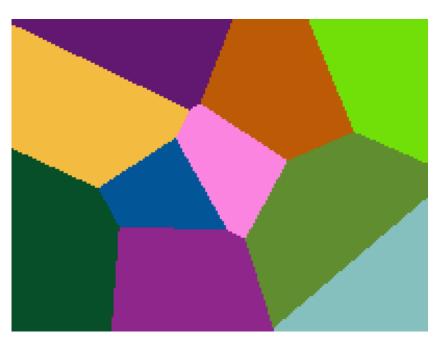
- > Project Goal
- > Explaining the EFT
- > Mechanical Verification
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The project goal

- > The goal of this bachelor project is to mechanically verify (or even disprove) that the algorithm as posed by Hesselink [1] correctly calculates the Euclidean Feature Transform (EFT), and does so in linear time complexity.
- > Mechanical Verification > Mathematical Proof

The Euclidean Feature Transform (EFT)





The EFT algorithm

- > The algorithm uses some clever tricks
 - Iterating the dimensions, using the same algorithm for solving the base case and the inductive step
- Reduces the problem to finding the one-dimensional EFT
- \rightarrow O(n) (n number of "pixels")

The EFT algorithm

```
OneFT(n, h):
    q \leftarrow 0; t[0] \leftarrow 0; at[0] \leftarrow 0
    for (k \leftarrow 1; k < n; k++)
           while (q \ge 0 \land f(t[q], at[q]) > f(t[q], k))
                  q \leftarrow q - 1
           if (q < 0)
                  a \leftarrow o: at [o] \leftarrow k
           else
                  w \leftarrow 1 + g(at[q], k)
                  if (w < n)
                          q \leftarrow q+1
                          t[q] \leftarrow w; at[q] \leftarrow k
```

```
t[q+1] \leftarrow n; at[q+1] \leftarrow n-1
for (i \leftarrow 0; i = q; i++)
      x1 \leftarrow t[i+1] - 1
      for (x \leftarrow t[j]; x = x1; x++)
             FT[x] \leftarrow \{at[i]\}
      for (p \leftarrow at[j] + 1; p = at[j+1]; p++)
             if(f(x_1, p) = f(x_1, at[i]))
                     FT[x_1] \leftarrow FT[x_1] \cup \{p\}
```

Mechanical Verification





Welcome to the PVS Specification and Verification System

- > Prototype Verification System (PVS 5.0)
 - SRI International, Computer Science Laboratory
- > Specification Language
- > Interactive Prover

PVS Specification Language

- > Based upon simple typed logic
- > Formal specification of the problem
 - Types
 - Definitions
 - Theorems / Lemmas

PVS Prover

- > Proof obligation
 - Logical sentence: $P_0 \wedge P_1 \wedge ... \wedge P_m \Rightarrow Q_0 \vee Q_1 \vee ... \vee Q_n$
- > Proof commands
 - Rewrite proof obligation to a logical equivalent statement
- > The Prover does not prove anything!
 - It is merely keeps a "smart" administration



PVS Prover - Example

Program Correctness

- > programs.pvs
 - Hoare-Triplets:
 - {P} S {Q}
 - While loops
 - 5 steps
 - Prove correctness and termination

Project Progress (done)

- > Learning PVS
 - Basics of the master course Automated Reasoning
- > Understanding the algorithm
- > Verified the mathematics
- > The algorithm
 - Proved on paper
 - Specified in PVS
- > 118 theorems/lemmas
 - 91 proven

Project Progress (todo)

- > Prove the algorithm
 - With PVS
- Optional: prove the mathematics behind iterating the dimensions
- > Write thesis

Evaluation

- Mechanically verifying a problem does not result in a deeper understanding of a problem
 - It does require a full understanding of the problem
- > PVS is a great tool for proving complex mathematical theorems
 - But, often it feels like you do a lot of trivial work that could somehow be automated

Thank you for your attention

Are there any questions?

References

[1] W. H. Hesselink, "Distance transforms and feature transform sets," May 2009. An extension and modification of the IPL paper.